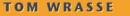
The Use of Underwater Robotic & Sonar Technology for Drowning Victim Recovery Presented by Tom Wrasse Underwater Warden



INVESTIGATION . INSPECTION . RECOVERY



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- ROV: » PILOT » INSTRUCTOR » CONSULTANT



# Introduction

# Tom Wrasse – Underwater Warden

- Certified VideoRay Instructor, Pilot and Consultant
- 30 years experience in law enforcement with the Wisconsin Department of Natural Resources
- VideoRay end user



INVESTIGATION \* INSPECTION \* RECOVERY





# Objectives

Drowning Statistics ROV background Classification types Applications Accessories Searches Basics Tactics Recoveries Training Case study information



### •Worldwide<sup>1</sup> - estimates

1063 unintentional drowning/day ~390,000/yr
Ranks 3<sup>rd</sup> for causes of unintentional deaths
96% occur in low – middle income countries
The highest rates are found in the regions of Africa, China and India

- United States
  - 10 drowning/day<sup>2</sup>, ~3650/yr
  - Ranks 5<sup>th</sup> for causes of unintentional deaths<sup>2</sup>
  - 1 in 5 or 20% are less than 14 years of age<sup>3</sup>
    80% are male<sup>3</sup>
  - •\$273 million (USD) in associated costs<sup>1</sup>

- Canada
  - 1.3 drowning/day<sup>9</sup>, ~467/yr
    Doply 4th for courses of uninter
  - Ranks 4<sup>th</sup> for causes of unintentional deaths<sup>9</sup>
  - •15% are less than 14 years of age<sup>9</sup>
  - ■83% are male<sup>9</sup>
  - •\$173 million (USD) in associated costs<sup>1</sup>

Australia

- .78 drowning/day<sup>7</sup>, ~285/yr
- **\$**85.5 million (USD) in associated costs<sup>1</sup>
- ■77% are male<sup>7</sup>
- 16% are 14 years of age or less<sup>7</sup>

# United Kingdom<sup>8</sup> 1.9 drowning/day, ~700/yr 68% are male 10% are 15 years of age or less



# Risk Factors to Natural Water Drowning

### Swimming ability

Failure to wear life jackets – 88% of those that drown related to a boating accident did not wear a life jacket <sup>4,5</sup>
Alcohol use – 70% of water related accidents

involve alcohol<sup>3,4,6</sup>



# Cold Water Drowning

# <58 F/14C</li> 90 minutes Mammalian diving reflex Shut down in order Begins when the face hits the water







### **Classifications:**

 Work Class – large vehicles, heavy payload capability, multi-person crews





### **Classifications:**

 Observation Class – small suitcase sized, lightweight, portable, easily deployed by one person





### **Classifications:**

Special Use – built for a specific task, not very common due to high associated costs



Observation Class – further defined
Micro - very small, "hobby" type, primarily a swimming eyeball used for inspections, shallow depths
Mini – small, equipped with camera, lights, manipulator and sensors



Applications:
Inspection
Observation
Documentation
Recovery
Sensory Platform

Application Fields (to name just a few): Aquaculture Law Enforcement •Offshore Oil and Gas Military Science and Research Potable Water Supply Infrastructure

## Video

- •Front high resolution color camera with tilt, rear/external black and white
- •HD is available with some modifications
- Has snapshot capability
- Video enhancements

# Lights LED's Video quality is improved where the lights are mounted separate of the camera Provide excellent dimming capability

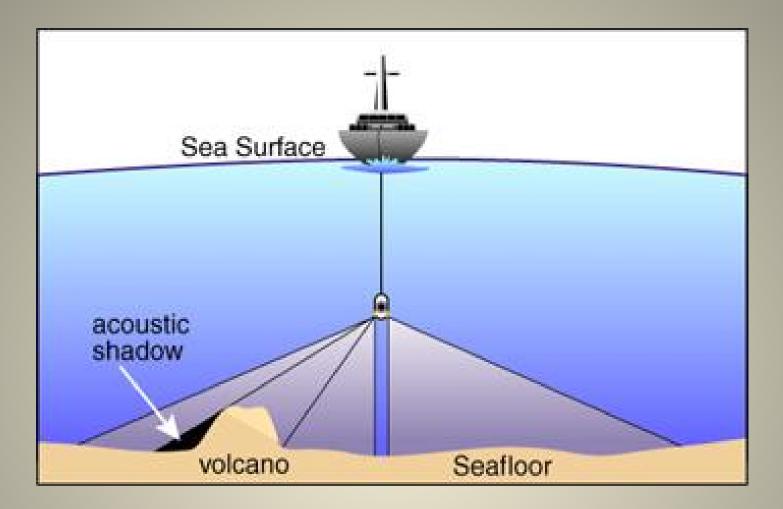


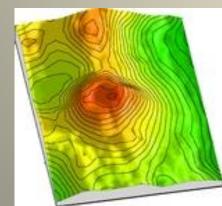
# Accessories to complement the mini-ROV

Sonar

Ability to "see" beyond the video Frequencies dictate the end result Practice required to interpret images Sonar Types Side Scan Towed Hull mounted GPS capabilities





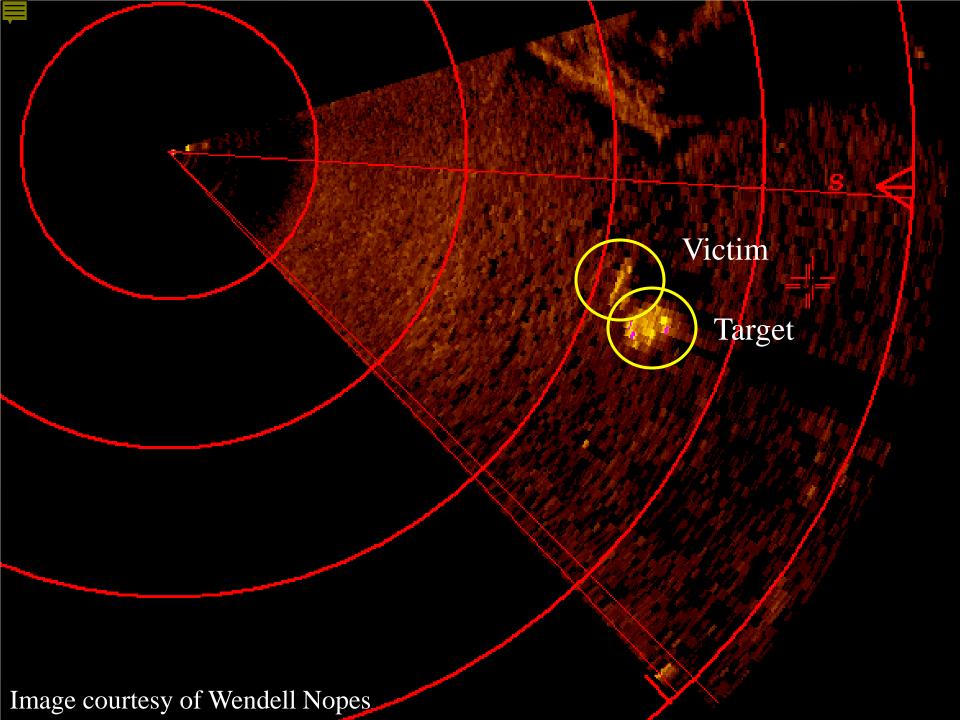


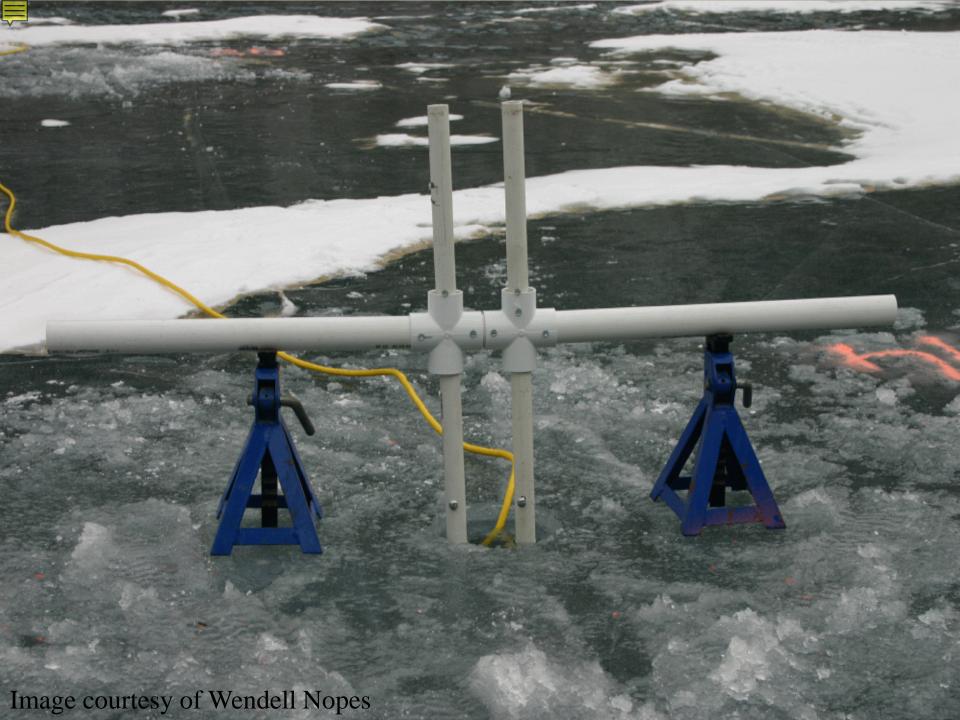
Side scan

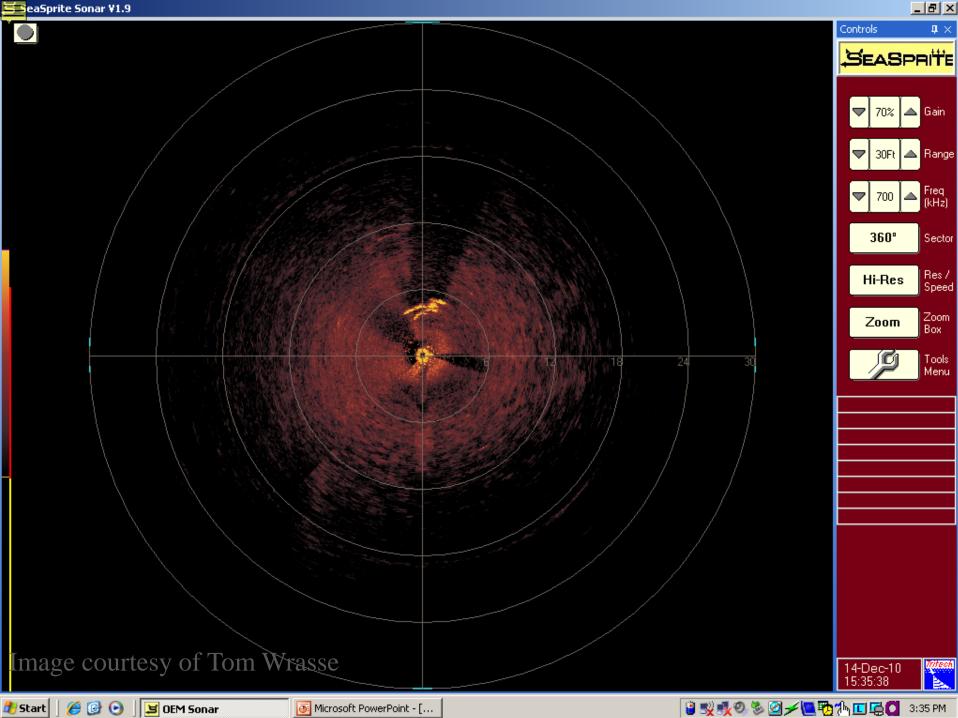




Sonar Types Mechanical Scanning ROV mounted Fixed mounted

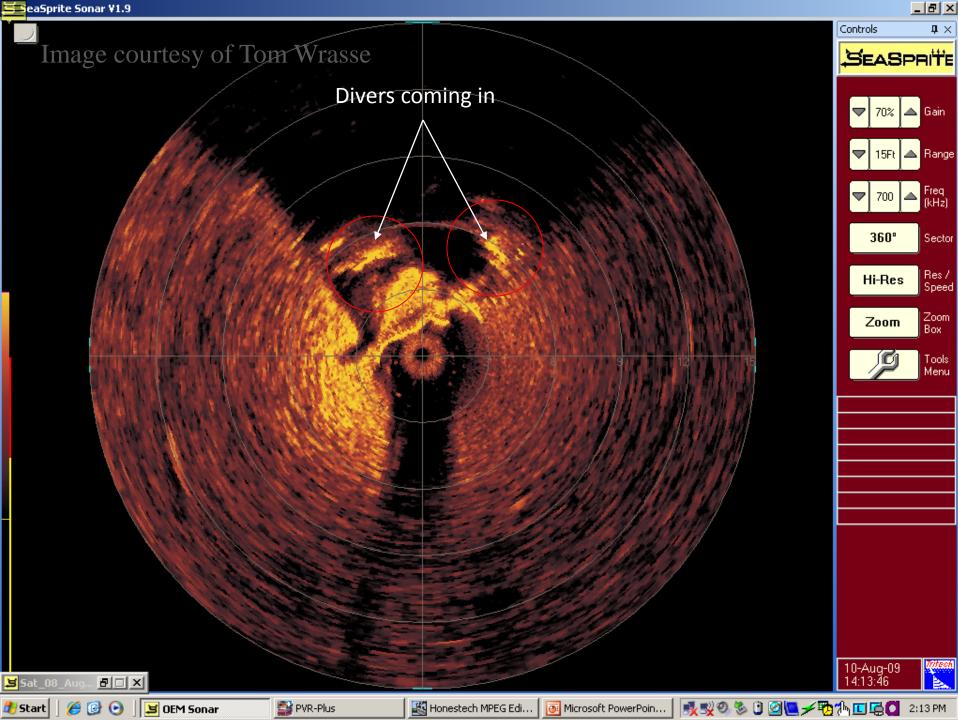






### Image courtesy of Tom Wrasse

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Sonar Types Multi-beam Scanning ROV mounted Fixed mounted

Review P900-45

Image courtesy of Craig Thorngren – Submerged Recovery and Inspection Services



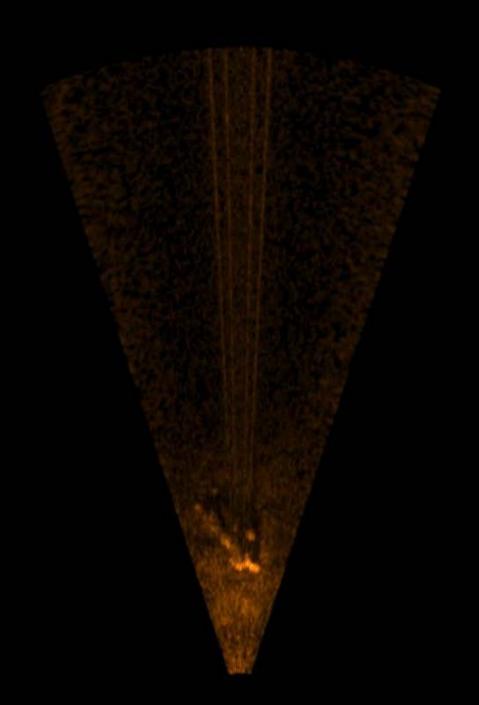


Image courtesy of Craig Thorngren – Submerged Recovery and Inspection Services



# Manipulators

- There is a wide range of manipulators available for most ROV's
- Typically single function
- Attachments for cutting heads
- Used in rescues/recoveries



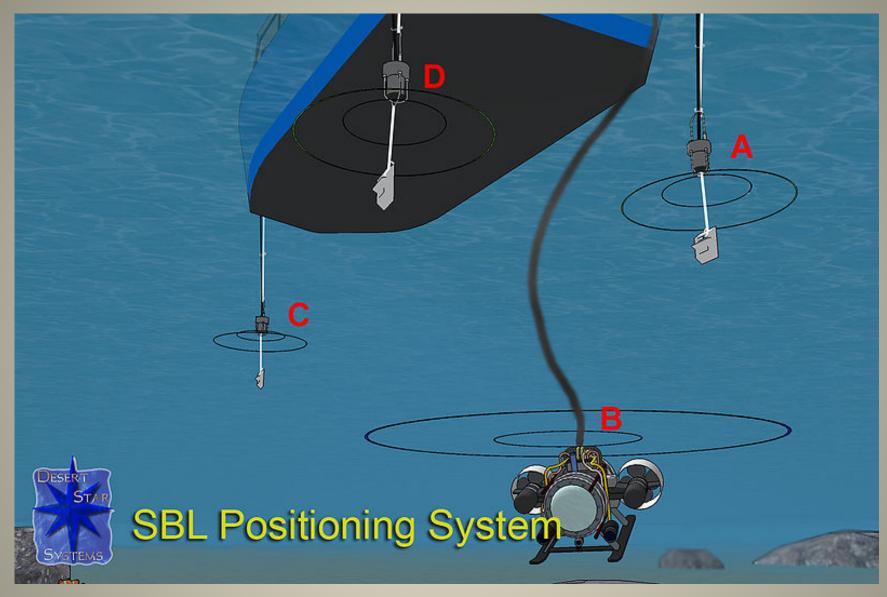
Tracking/Navigation Systems
Acoustic – interprets sound pulses through pingers, transponders and responders

- Long Baseline LBL
- Short Baseline SBL
- Ultra Short Baseline USBL









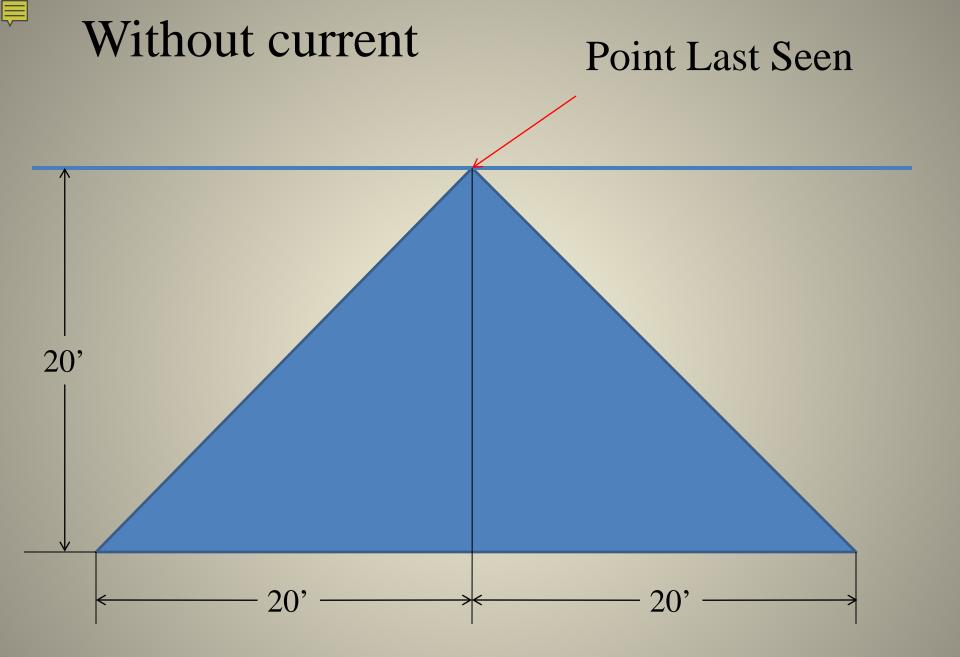


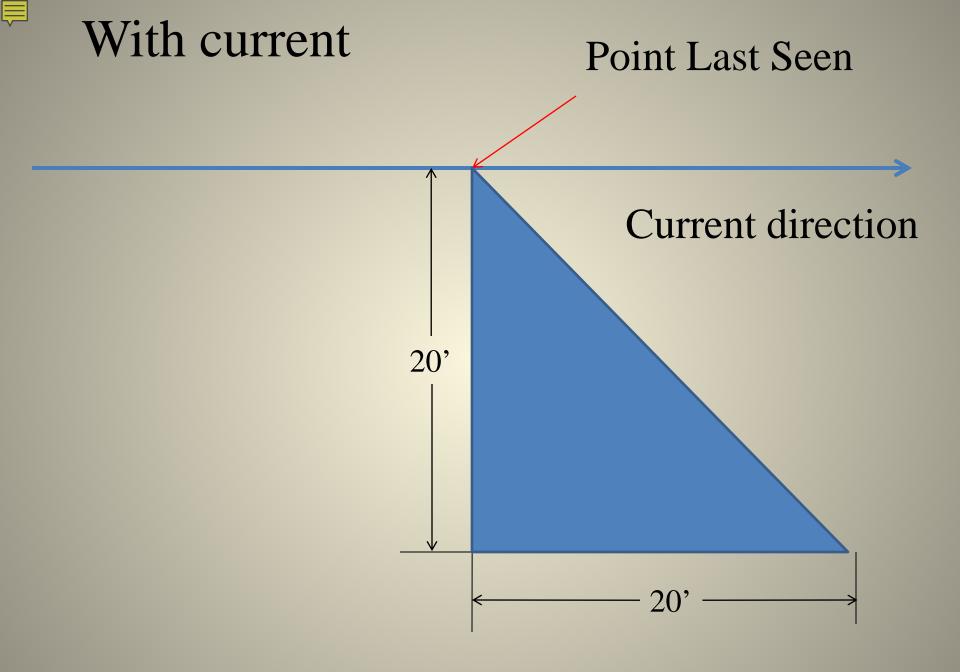
### Tracking/Navigation Systems Non-acoustic Tether based – uses a series of sensor embedded nodes Acceleration - distance Magnetics - direction Rate-gyro – position Provides position history GPS enabled

# Searches

Where to begin Point Last Seen – interviewing as many "witnesses" as possible Triangulate Mark the spot Eliminate sectors •Gather all the facts prior to entering the water

Where to begin What area to search Wind, current, tide, water depth Victim descent Without current •With current Bayesian Search Theory<sup>10</sup> – concept of evidential probability through mathematics Measurable, mapable, obtainable



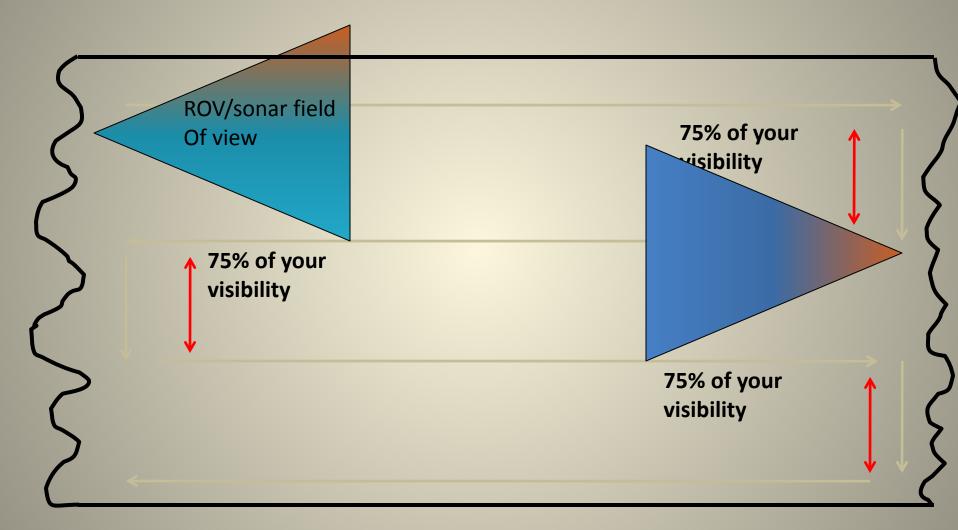


## Where to begin Method to search Apply the tools right for the job Adjust the job to the tools available Side Scan – large area coverage Scanning – mid range coverage Tracking/navigation system – ensures complete coverage ROV w/video and sonar – small search areas and target truthing Targets need to be marked

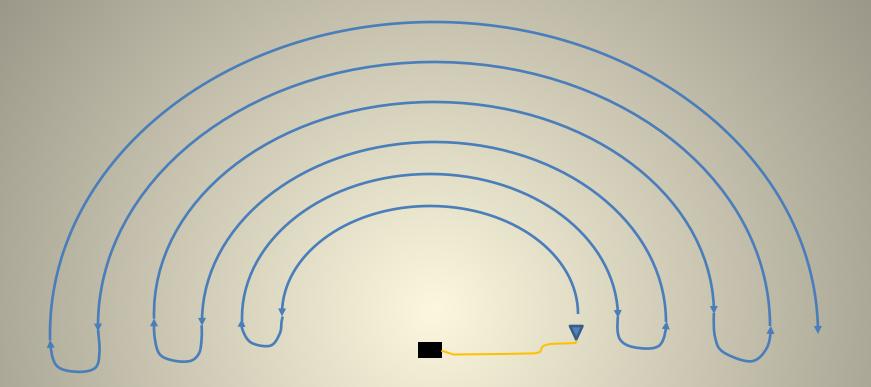
Search tactics Search Area Divided into smaller sections Primary – secondary sections Documentation – systematic coverage identifying sections completed and those yet to be

Search tactics
Search Patterns
Overlap field of view - ~75%
Parallel tracks – back and forth
Fan/arc – a series of concentric arcs
Circle – a series of concentric circles

#### Parallel Track Pattern



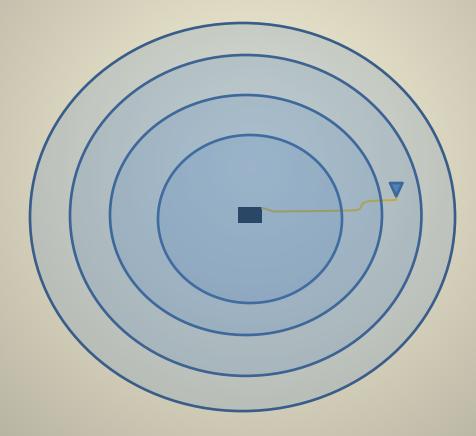




#### Fan/arc Pattern



# Circle Pattern



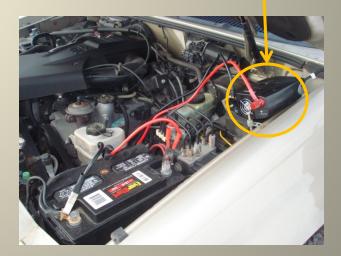
# Operations

#### Wall outlet

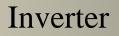
# Shore based Vessel Power Source



Generator









Search tactics Target Marking Buoys – surface markings Acoustic – subsurface markings Active – pingers that broadcast a signal to a tracking system Passive – reflect sonar waves Tracking/navigation – known fixed point that can be duplicated Holding location



Techniques Diver descent – following the tether to the target •Grip and pull – manipulator and tether used to retrieve the target Recovery lines Hooking Threading Wrapping



# Training

VendorIn-houseRefreshers



#### **Case Studies**

Rescue Retention Pond Marina Helicopter Royal Netherlands Navy



# Numbers

Vendors – only one vendor contacted provided numbers VideoRay – 40-50 recoveries made Agencies SARbot UK – St Louis County Sheriff Rescue Wisconsin Department of Natural Resources Individuals

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# Acknowledgments

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