

Defender Deep Water System **Navigation Package**

The Defender Deep Water System Navigation Package enhances autonomous control at depths up to 1,000m. It includes a Doppler Velocity Log (DVL) for tracking the ROV's position along the sea bottom and estimating distance traveled using "dead reckoning" navigation. A GPS antenna corrects the position at the surface. The software upgrade integrates these sensors, offering station keeping, mission planning, dynamic positioning, and data export. A USBL system can be added for operations beyond the DVL's range.

DVL SPECIFICATIONS

4km **Depth Rating**

500kHz **Frequency of Operation Beam Width** 2.9 degrees

> Configuration 4-beam Janus array convex

> > transducer, 25 degree beam angle

Minimum Altitude 0.1m100m Maximum Altitude

GPS SPECIFICATIONS

1.000m **Depth Rating Horizontal Position**

Accuracy 2.5m

29s Time-to-first-fix

-166 dBm **Sensitivity**



GREENSEA IQ UPGRADES

Station Keeping

Reacquisition

Mission Planning

Dynamic Positioning

*This is only the navigation portion of the Deep Water system. A Deep Water float block, Subsea Batteries, and fiber tether are required for the vehicle to reach 1,000m depth. An optional 1,000m rated Sonar is also available.

USBL (OPTIONAL)

Depth Rating Acoustic Range

Range Resolution Velocity-of-Sound Range

Becaon Velocity

Communications

1000m

1 km radius horizontal, 1km vertical

±50mm

1300ms-1 to 1700ms-1

Active Doppler compensation, up to

15kts (28kph)

Broadband spread spectrum encoding,

24-32kHz, 100 baud. Multi-tiered

Acoustic Protocol